

# INTERIOR-POINT METHODS AS AN ALTERNATIVE TO ESTIMATE THE CONTEXT-FREE GRAMMAR PARAMETERS

Autor: Esther Sofía Mamián López

Orientador: Dr. Aurelio Ribeiro Leite de Oliveira

Co-orientador: Dr. Fredy Angel Amaya Robayo

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- ♣ Introduction
- ♣ Language and Grammar
- ♣ Interior-Point Method
- ♣ Numerical Result
- ♣ Conclusion and Future Propose

# Introduction

## Language Modeling

### Goal

Compute the probability of a sentence or sequence of words.

### Application

- Machine Translation
  - $P(\text{high winds tonight}) > P(\text{large winds tonight})$
- Speech Recognition
  - $P(\text{I saw a van}) \gg P(\text{eyes awe of an})$

## Language model

- Let  $\chi_i \in \Sigma^*$  a sentence or a word.  
A model that computes either of these  $P(\chi)$  or  $P(\chi_1, \chi_2, \dots, \chi_n)$ , is called a language model.

## Language model

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A model that computes either of these  $P(\chi)$  or  $P(\chi_1, \chi_2, \dots, \chi_n, )$ , is called a language model.
- Better call **Grammar**

# Language and Grammar

## Context-free Grammar and Probabilistic Context-Free Grammar

### Context-Free Grammar

Context-free grammar were first used in the study of human language. One way understanding the relationship of terms such as *noun*, *verb* and *preposition* and their respective phrase leads to a natural recursion because noun phrases may appear inside verbs phrases and vice versa. Context-free grammar can capture important aspects of these relationships.

# Language and Grammar

## Context-free Grammar and Probabilistic Context-Free Grammar

### Grammar

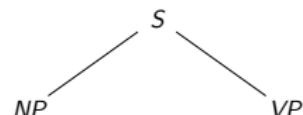
- |                                |  |
|--------------------------------|--|
| 1) $S \rightarrow NP\ VP$      | 7) $NP \rightarrow NP\ PP$             |
| 2) $PP \rightarrow P\ NP$      | 8) $NP \rightarrow \text{astronomers}$ |
| 3) $VP \rightarrow V\ NP$      | 9) $NP \rightarrow \text{eyes}$        |
| 4) $VP \rightarrow VP\ PP$     | 12) $NP \rightarrow \text{saw}$        |
| 5) $P \rightarrow \text{with}$ | 10) $NP \rightarrow \text{starts}$     |
| 6) $V \rightarrow \text{saw}$  | 11) $NP \rightarrow \text{telescopes}$ |

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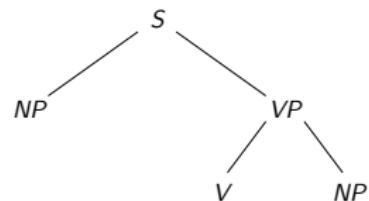


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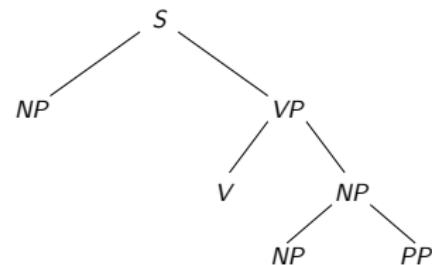


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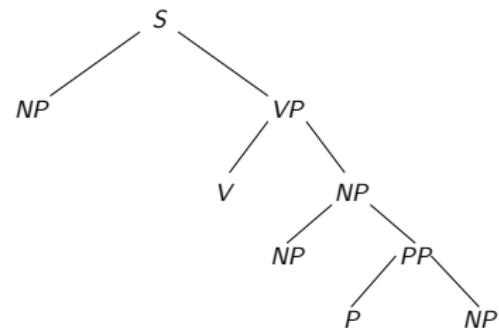


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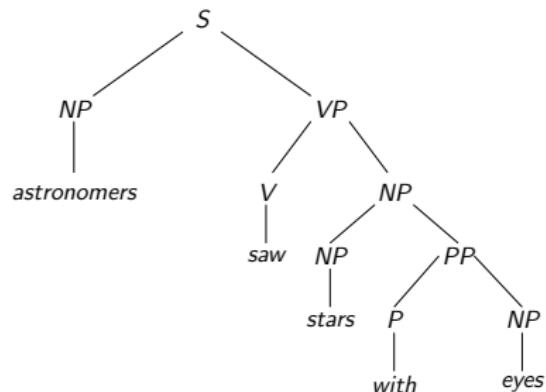


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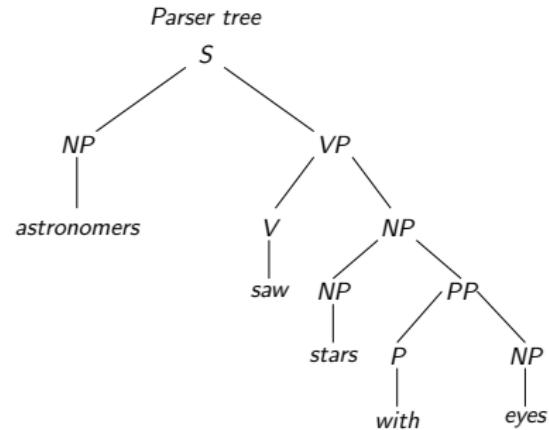


# Language and Grammar

## Context-free Grammar and Probabilistic Context-Free Grammar

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$\chi = \text{astronomers saw stars with eyes}$

$\eta = \text{saw saw saw with saw}$

# Language and Grammar

## Context-free Grammar and Probabilistic Context-Free Grammar

### Grammar

- 1)  $S \rightarrow NP\ VP$
- 2)  $PP \rightarrow P\ NP$
- 3)  $VP \rightarrow V\ NP$
- 4)  $VP \rightarrow VP\ PP$
- 5)  $P \rightarrow with$
- 6)  $V \rightarrow saw$
- 7)  $NP \rightarrow NP\ PP$
- 8)  $NP \rightarrow astronomers$
- 9)  $NP \rightarrow eyes$
- 10)  $NP \rightarrow starts$
- 11)  $NP \rightarrow telescopes$

A grammar describes a Language

# Language and Grammar

## Context-free Grammar and Probabilistic Context-Free Grammar

### Definition

A context-free grammar is a 4-tuple  $G = (\Sigma, N, S, P)$  where:

- $\Sigma$  is a finite set of terminal symbols.
- $N$  is a finite set of nonterminal symbols, with  $N \cap \Sigma = \emptyset$ .
- $S \in N$  is the start symbol.
- $P$  is a finite set of rules/production of the form  $A \longrightarrow \gamma$ , where  $A \in N$  and  $\gamma$  is a sentential form, i.e.  $\gamma \in (N \cup \Sigma)^*$ .

# Language and Grammar

## Context-free Grammar and Probabilistic Context-Free Grammar

### Definition

A context-free grammar is in Chomsky Normal Form (CNF) if every rule is of the form  $A \rightarrow BC$  e  $A \rightarrow a$ , where  $A, B, C \in N$  and  $a \in \Sigma$ .

### Definition

The language  $L(G)$  generate from  $G$  is the set of terminal strings that have derivation from start symbol. That is,

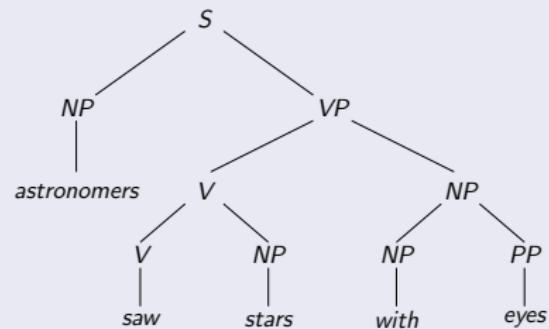
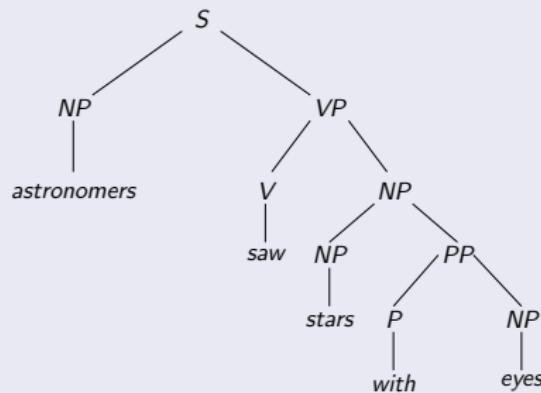
$$L(G) = \{\chi \in \Sigma^+ : S \xrightarrow{*} \chi\},$$

where  $\Sigma^+$  is a set of string/sentence in  $\Sigma$ .

# Language and Grammar

## Context-free Grammar and Probabilistic Context-Free Grammar

### Ambiguity



# Language and Grammar

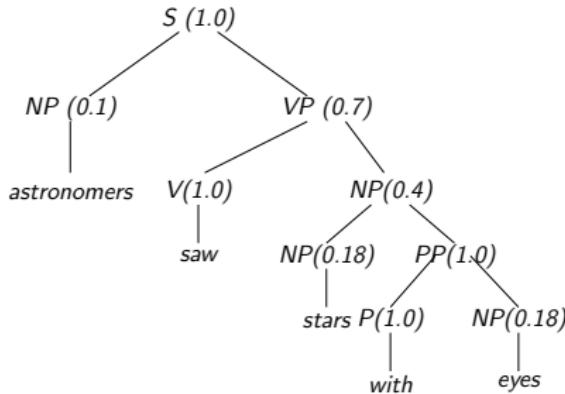
## Context-free Grammar and Probabilistic Context-Free Grammar

### Definition

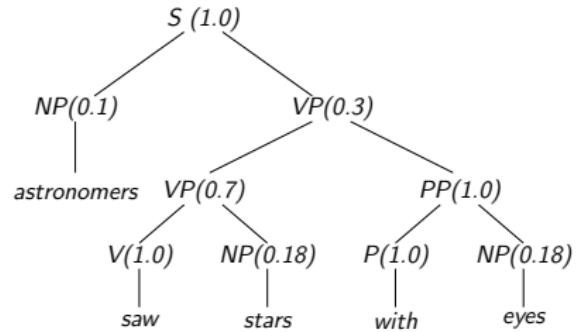
A *Probabilistic Context-Free Grammar* is a 5-tuple  $G = (\Sigma, N, S, P, p)$  where:

- $\Sigma$  is a finite set called *terminal symbols*.
- $N$  is a finite set called *nonterminal symbols*. Where  $N \cap \Sigma = \emptyset$ .
- $S \in N$  is the start symbol.
- $P$  is a finite set of rules/production of the form  $A \longrightarrow \gamma$ , where  $A \in N$  and  $\gamma$  is a sentential form .  $\gamma \in (N \cup \Sigma)^*$ .
- $p$  is a probability function
  - $p : P \rightarrow [0, 1]$
  - $\forall A \in N, \sum_{(A \longrightarrow \alpha) \in \Gamma_A} p(A \longrightarrow \alpha) = 1$

Parse tree t1



Parse tree t2

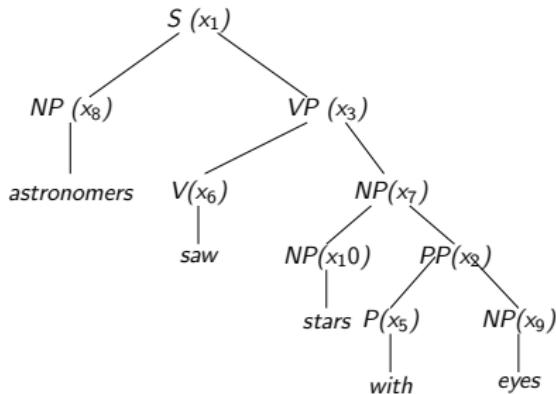


$$p(t1) = 1.0 \times 0.1 \times 0.7 \times 1.0 \times 0.4 \times 0.18 \times 1.0 \times 1.0 \times 0.18 = 0.0009072$$

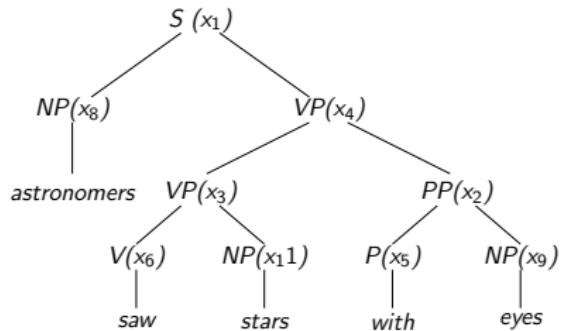
$$p(t2) = 1.0 \times 0.1 \times 0.3 \times 0.7 \times 1.0 \times 1.0 \times 0.18 \times 1.0 \times 0.18 = 0.0006804$$

$$p(\chi) = p(t1) + p(t2) = 0.0015876$$

Parse tree t1



Parse tree t2



$$p(t1) = x_1 x_8 x_3 x_6 x_7 x_{10} x_2 x_5 x_9$$

$$p(t2) = x_1 x_8 x_4 x_3 x_2 x_6 x_{11} x_5 x_9$$

$$p(\chi) = p(t1) + p(t2) = x_1 x_8 x_3 x_6 x_7 x_{10} x_2 x_5 x_9 + x_1 x_8 x_4 x_3 x_2 x_6 x_{11} x_5 x_9$$

# Language and Grammar

## Likelihood Function

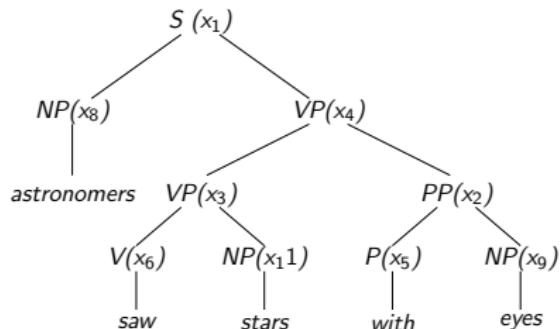
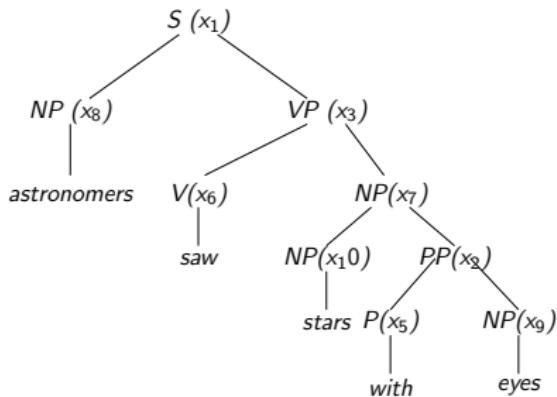
### Learning Grammar/Training Grammar

- A corpus  $\Omega$  is a big finite set of sentences and words of a language.
- We train parameters of our model on a training set. A training set is a subset the corpus.
- We test the model's performance on data of corpus that we haven't seen.

### Definition

*In the context-free grammar the likelihood function of a language corpus  $\Omega$  is*

$$Pr(\Omega|G_p) = \prod_{\chi \in \Omega} Pr(\chi|G_p).$$



$$p(t1) = x_1 x_8 x_3 x_6 x_7 x_{10} x_2 x_5 x_9$$

$$p(t2) = x_1 x_8 x_4 x_3 x_2 x_6 x_{11} x_5 x_9$$

$$p(\chi) = p(t1) + p(t2) = x_1 x_8 x_3 x_6 x_7 x_{10} x_2 x_5 x_9 + x_1 x_8 x_4 x_3 x_2 x_6 x_{11} x_5 x_9$$

$$p(\eta) = p(t1) + p(t2) + p(t3) = x_1 x_8 x_3 x_6 x_7 x_{10} x_2 + x_1 x_4 x_3 x_2 x_6 x_{11} + x_1^2 x_2 x_8 x_4 x_3^3$$

## likelihood function

If  $\Omega = \{\chi, \eta\}$  we have that likelihood function is  $Pr(\Omega | G_p) = p(\chi) \times p(\eta)$

# Language and Grammar

## Optimization Problem

### Problema

$$\begin{aligned} & \text{maximize} && Pr(\Omega | G_p) \\ & \text{such as} && \sum_{x_i \in \Psi_A} x_i = 1 \\ & && 0 \leq x_i \leq 1, \quad i = 1, \dots, |P|, \end{aligned}$$

where  $\Psi_A$  is finite set of rules probabilities with the same antecedent.

# Interior Point Method

## Logarithmic Barrier Method

$$\left\{ \begin{array}{l} \text{Maximize } f(x) \\ \text{Such as } Ax = b \\ 0 \leq x \leq u \end{array} \right. \xrightleftharpoons{\mu \rightarrow 0} \left\{ \begin{array}{l} \text{Minimize } f(x) - \mu \left( \sum_{i=1}^n \ln(x_i) + \sum_{i=1}^n \ln(v_i) \right) \\ \text{Such as } Ax = b \\ x + v = u, \\ \text{com } \mu > 0. \end{array} \right.$$

where  $f : \Re^n \longrightarrow \Re$ ,  $x \in \Re^n$ ,  $A \in \Re^{m \times n}$ ,  $b \in \Re^m$  e  $u \in \Re^n$ .

For each fixed value  $\mu$  and using the associated Lagrangiano

$$\mathcal{L}(x, v, y, w) = f(x) - \mu \left( \sum_{i=1}^n \ln(x_i) + \sum_{i=1}^n \ln(v_i) \right) + y^T(b - Ax) + w^T(u - v - x).$$

# Interior Point Method

## Logarithmic Barrier Method

$$\begin{pmatrix} \nabla f(x) - \mu X^{-1}e + A^T y - w \\ w - \mu V^{-1}e \\ Ax - b \\ u - v - x \end{pmatrix} = 0.$$

$$\begin{pmatrix} H(x) + \mu X^{-2} & 0 & A^T & -I \\ 0 & \mu V^{-2} & 0 & I \\ A & 0 & 0 & 0 \\ I & I & 0 & 0 \end{pmatrix} \begin{pmatrix} \Delta x \\ \Delta v \\ \Delta y \\ \Delta w \end{pmatrix} = \begin{pmatrix} r_d \\ r_b \\ r_p \\ r_u \end{pmatrix},$$

# Interior Point Method

## Logarithmic Barrier Method

$$\begin{pmatrix} H(x) + \mu X^{-2} & 0 & A^T & -I \\ 0 & \mu V^{-2} & 0 & I \\ A & 0 & 0 & 0 \\ I & I & 0 & 0 \end{pmatrix} \begin{pmatrix} \Delta x \\ \Delta v \\ \Delta y \\ \Delta w \end{pmatrix} = \begin{pmatrix} r_d \\ r_b \\ r_p \\ r_u \end{pmatrix},$$

onde  $H(x) = \nabla^2 f(x)$ ,  $r_d = \mu X^{-1} - A^T y - w - \nabla f(x)$ ,  $r_b = \mu V^{-1} e - w$ ,  
 $r_p = b - Ax$  e  $r_u = u - x - v$

# Interior Point Method

## Logarithmic Barrier Primal-Dual Method

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### Algorithm 1.1: Barreira Logarítmica Canalizado

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**Dados:**  $(x^0, v^0) > 0$ ,  $y^0$ ,  $w^0$ ,  $\sigma = \frac{1}{\sqrt{n}}$   $k = 1$

**inicio**

**Calcular** o valor para  $\mu = \sigma \frac{\gamma}{n}$ , onde  $\gamma = (v^k)^t w^k$ ;

**Calcular** as direções  $\Delta x, \Delta y$  resolvendo o sistema linear:

$$\begin{pmatrix} \hat{H} & A^T \\ A & 0 \end{pmatrix} \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix} = \begin{pmatrix} r_d + V^{-1}W(r_u - W^{-1}r_b) \\ r_p \end{pmatrix} \quad \text{onde } \hat{H} = H(x) + \mu X^{-2} + V^{-1}W ;$$

**Determinar**  $\alpha$  usando o teste da razão;

**Atualizar** o passo:

$$(x^{k+1}, v^{k+1}, y^{k+1}, w^{k+1}) = (x^k, v^k, y^k, w^k) + \alpha(\Delta x, \Delta v, \Delta y, \Delta w);$$

    se o critério de parada é satisfeito **então**

        | **parar**;

**senão**

        | **faça**  $k = k + 1$  e volte ao Passo 2;

**fim se**

**fin**

# Interior Point Method

## Primal-Dual Logarithmic Barrier Method

$$\begin{array}{ll}\text{minimize} & f(x) \\ \text{such as} & Ax = b \\ & 0 \leq x \leq u\end{array}$$

onde  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $x \in \mathbb{R}^n$ ,  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$  e  $u \in \mathbb{R}^n$ .

$$\begin{pmatrix} \nabla f(x) - \mu X^{-1}e + A^T y - w \\ w - \mu V^{-1}e \\ Ax - b \\ x + v - u \end{pmatrix} = 0.$$

# Interior Point Method

## Primal-Dual Logarithmic Barrier Method

$$\begin{array}{ll}\text{minimize} & f(x) \\ \text{such as} & Ax = b \\ & 0 \leq x \leq u\end{array}$$

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$XZe = \mu e$

$$\begin{pmatrix} \nabla f(x) - \overset{Z}{\cancel{\mu X^{-1}e}} + A^T y - w \\ w - \cancel{\mu V^{-1}e} \\ Ax - b \\ x + v - u \end{pmatrix} = 0.$$

# Interior Point Method

## Primal-Dual Logarithmic Barrier Method

$$\begin{array}{ll}\text{minimize} & f(x) \\ \text{such as} & Ax = b \\ & 0 \leq x \leq u\end{array}$$

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$VWe = \mu e$

$$\begin{pmatrix} \nabla f(x) - z + A^T y - w \\ w - \mu V^{-1} e \\ XZe - \mu e \\ Ax - b \\ x + v - u \end{pmatrix} = 0.$$

# Interior Point Method

## Primal-Dual Logarithmic Barrier Method

$$\begin{array}{ll}\text{minimize} & f(x) \\ \text{such as} & Ax = b \\ & 0 \leq x \leq u\end{array}$$

onde  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $x \in \mathbb{R}^n$ ,  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$  e  $u \in \mathbb{R}^n$ .

$$\begin{pmatrix} \nabla f(x) - z + A^T y - w \\ VWe - \mu e \\ XZe - \mu e \\ Ax - b \\ x + v - u \end{pmatrix} = 0, \quad (x, v, w, z) \geq 0, \quad \mu > 0.$$

$$\begin{pmatrix} H(x) & 0 & -I & A^T & -I \\ 0 & W & 0 & 0 & V \\ Z & 0 & X & 0 & 0 \\ A & 0 & 0 & 0 & 0 \\ I & I & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \Delta x \\ \Delta v \\ \Delta z \\ \Delta y \\ \Delta w \end{pmatrix} = \begin{pmatrix} r_d \\ r_b \\ r_c \\ r_p \\ r_u \end{pmatrix}$$

$$r_d = z - \nabla f(x) - A^t y - w, \quad r_c = \mu e - X Z e, \quad r_b = \mu V^{-1} e - w, \quad r_p = b - Ax \\ \text{e } r_u = u - x - v$$

# Interior Point Method

## Primal-Dual Logarithmic Barrier Method

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### Algorithm 1.2: Primal-Dual Canalizado

---

**Dados:**  $y^0, (x^0, v^0, w^0, z^0) > 0, \sigma = \frac{1}{2n}, k = 1.$

**inicio**

**Escolher**  $\mu = (\frac{\gamma}{2n})$ , onde  $\gamma = (x)^t z + (v)^t w;$

**Resolver** o sistema linear

$$\begin{pmatrix} \hat{H} & A^T \\ A & 0 \end{pmatrix} \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix} = \begin{pmatrix} r_d - X^{-1}r_c + V^{-1}(r_b - wr_u) \\ r_p \end{pmatrix},$$

onde  $\hat{H} = H(x) + X^{-1}Z + V^{-1}W.$

**Determinar**  $\alpha$  usando o teste da razão *backtracking*;

**Atualizar** o passo  $(x^{k+1}, v^{k+1}, z^{k+1}, y^{k+1}, w^{k+1}) = (x^k, v^k, z^k, y^k, w^k) + \alpha(\Delta x, \Delta v, \Delta z, \Delta y, \Delta w);$

**se** o critério de parada é satisfeito **então**

        | **parar**;

**senão**

        | **faça**  $k = k + 1$  e volte ao início;

**fim se**

**fin**

---

# Numerical Result

Tamanho amostra	Method	Iteration	Time (sec)	Perplexity
20	Logarithmic Barrier	23	14,6692	3,3422
	Primal dual Logarithmic Barrier	9	8,2426	3,5171
500	Logarithmic Barrier	19	670, 4786	3,4382
	Primal dual Logarithmic Barrier	1	64, 7130	3,4422
4000	Logarithmic Barrier	20	12448, 4759	3,4382
	Primal dual Logarithmic Barrier	1	837, 2390	3,4382

Tabela : Numerical Result of the Grammar 1 (5,12,25)

Tamanho amostra	Method	Iteration	Time (sec)	Perplexity
20	Logarithmic Barrier	8	27,6678	19,4277
	Primal dual Logarithmic Barrier	8	28,4952	22,9811
500	Logarithmic Barrier	8	379, 3173	19,5804
	Primal dual Logarithmic Barrier	8	314, 8892	22,9811
4000	Logarithmic Barrier	17	28498, 3234	19,3310
	Primal dual Logarithmic Barrier	8	9031, 0355	23,0644

Tabela : Numerical Result of the Grammar 2 (14,13,47)

# Numerical Result

Tamanho amostra	Method	Iteration	Time (sec)	Perplexity
20	Logarithmic Barrier	23	14,6692	3,3422
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Perplexidade por palavra Inside-Outside				25, 424

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Tamanho amostra	Method	Iteration	Time (sec)	Perplexity
20	Logarithmic Barrier	8	27,6678	19,4277
	Primal dual Logarithmic Barrier	8	28,4952	22,9811
500	Logarithmic Barrier	8	379, 3173	19,5804
	Primal dual Logarithmic Barrier	8	314, 8892	22,9811
4000	Logarithmic Barrier	17	28498, 3234	19,3310
	Primal dual Logarithmic Barrier	8	9031, 0355	23,0644

Tabela : Numerical Result of the Grammar 2 (14,13,47)

# Conclusion

- The approach of interior point methods is very robust, converging when the value of stop criterion  $\epsilon$  is extremely low.
- The times obtained for convergence, iteration and perplexity shows that further studies testing these methods in big grammars are very promising, and eventually, it could be used as an alternative in natural language.

# Future Propose

- To use C++ for implementing the methods.
- To implement a variant predictor-corrector Logarithmic Barrier Method and predictor-corrector Primal-Dual Logarithmic Barrier Method. The number of iterations required is expected to be lower.
- To search for another approaches to calculate the Hessian.
- To implement an hybrid approach between the Inside-Outside and Interior-Point methods.

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